

# SureStep™ STEPPING SYSTEMS

## Introducing SureStep™ Stepping Systems

### High Performance Microstepping Drive with High Torque Stepping Motors

Open-loop stepping systems provide simple and accurate control of position and speed where lower power and cost are considerations. Pulses (or "step" and "direction" signals) from the *DirectLOGIC* family of PLCs or other indexers and motion controllers are "translated" by the microstepping drive into precise movement of the stepping motor shaft. The *SureStep™* stepping motors use 2-phase technology with 200 full steps per revolution or 1.8° per full step. Older type stepping motor drives, which operate stepping motors in full step mode, can result in stalling or lost motion due to potential problems with low speed mechanical vibration (usually between 100 to 200 RPM). To minimize this vibration problem, the *SureStep* microstepping drive uses advanced microstepping technology with selectable step sizes of 400 steps per revolution ( $\div 2$ ), 1,000 steps per revolution ( $\div 5$ ), 2,000 steps per revolution ( $\div 10$ ), and 10,000 steps per revolution ( $\div 50$ ). The equation below relates the PLC pulse output frequency to *SureStep* motor speed and stepping angle:



### Stepping Motor RPM = (A ÷ B) x (60 seconds/minute)

where    A = PLC output frequency (steps of pulses per second)  
             B = microstepping motor drive resolution selection  
                     (steps/revolution – *SureStep™* provides 400, 1,000, 2,000, and 10,000 steps/revolution as possible settings)

Maximum Potential Speed Chart				
Direct LOGIC PLC Pulse Frequency	SureStep™ Drive Selection (Steps/Rev)			
	400 Steps/Rev	1000 Steps/Rev	2000 Steps/Rev	10,000 Steps/Rev
5,000Hz	750RPM	300RPM	150RPM	30RPM
7,000Hz	1050RPM	420RPM	210RPM	42RPM
10,000Hz	1500RPM	600RPM	300RPM	60RPM
25,000Hz	3750RPM	1500RPM	750RPM	150RPM

Formula	RPM	Steps/Sec A		Steps/Rev B		Sec/Min
<b>Example 1:</b>	<b>1,500</b>	<b>= 10,000</b>	<b>÷</b>	<b>400</b>	<b>X</b>	<b>60</b>
<i>DL06 with 10kHz Built-in Pulse Output</i>						
<b>Example 2:</b>	<b>1,500</b>	<b>= 25,000</b>	<b>÷</b>	<b>1,000</b>	<b>X</b>	<b>60</b>
<i>Hx-CTRI0 with 25kHz Pulse Output</i>						
<b>Example 3:</b>	<b>3,000</b>	<b>= 20,000</b>	<b>÷</b>	<b>400</b>	<b>X</b>	<b>60</b>
<i>Hx-CTRI0 using 20kHz Pulse Output</i>						

**Microstepping Drive**  
**STP-DRV-4035**



**NEMA 17 Stepper Motor**  
**STP-MTR-17048**



**NEMA 23 Stepper Motor**  
**STP-MTR-23055**



**NEMA 23 Stepper Motor**  
**STP-MTR-23079**



**NEMA 34 Stepper Motor**  
**STP-MTR-34066**



**Stepper Motor Extension Cable**  
**STP-EXT-020**

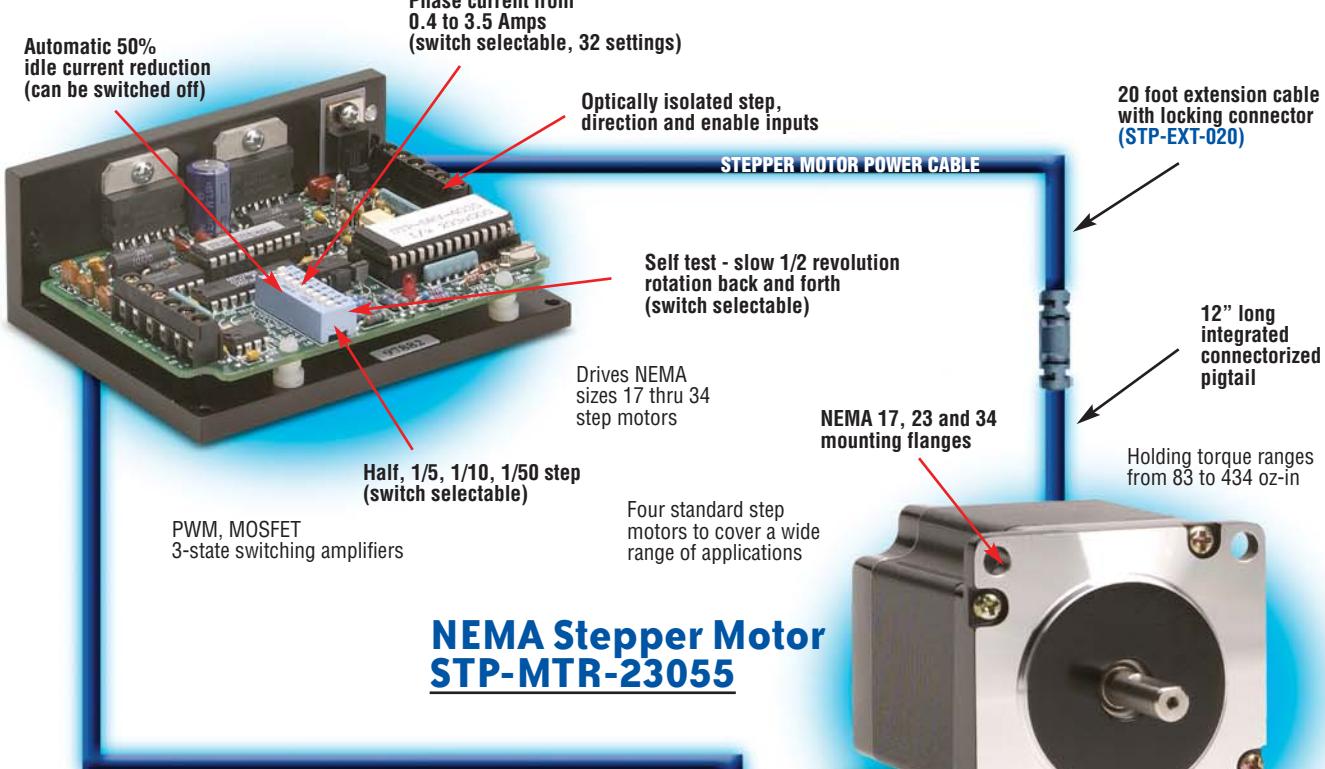


**Stepper Motor Power Supply**  
**STP-PWR-3204**

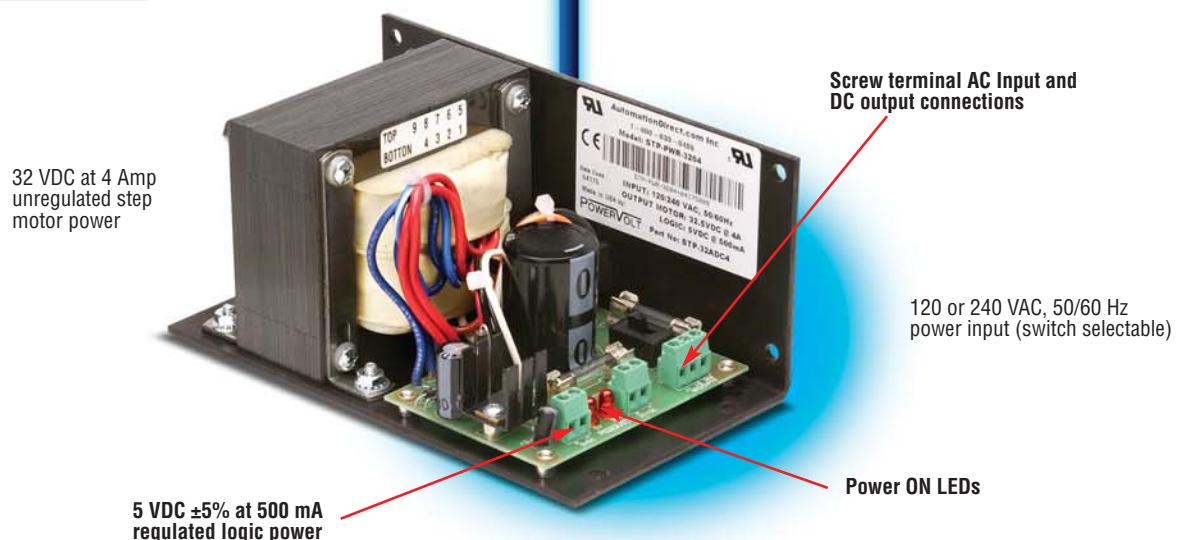


# Surestep™ STEPPING SYSTEMS

## 2-Phase Microstepping Drive STP-DRV-4035

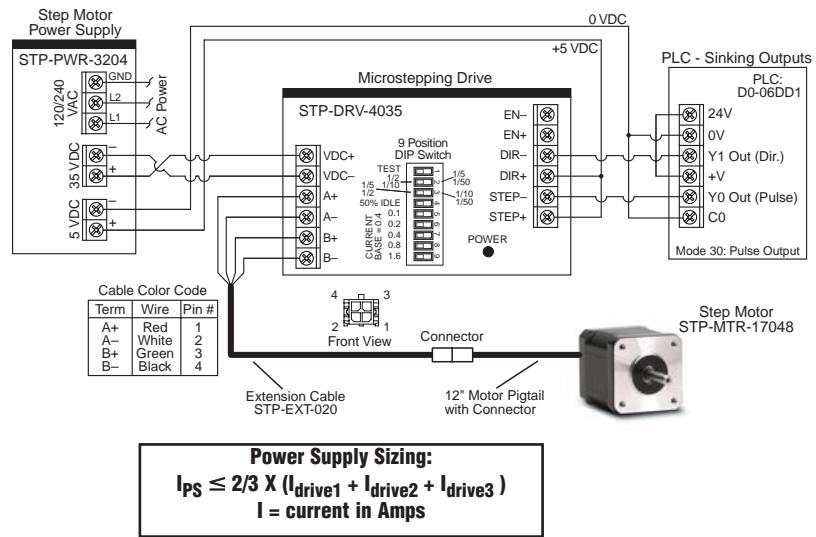


## Stepper Motor Power Supply STP-PWR-3204

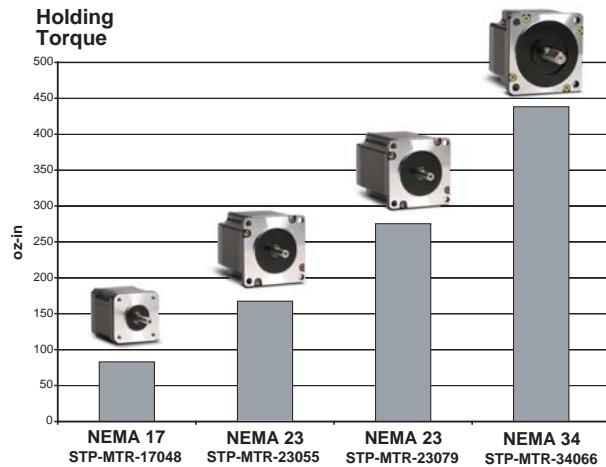


# SureStep™ STEPPING SYSTEMS

**SureStep™ stepping systems...four standard systems simplify your choice**



**Low-cost stepping systems from AUTOMATIONDIRECT...plug and play...it's that easy**



## One-size-fits-all microstepping drive

- Ultimate in simplicity
- One standard microstepping drive to operate any of four standard motors
- Onboard screw terminals for easy hook-up
- Optically-isolated inputs ready for +5 VDC logic from DirectLOGIC PLCs
- No software or add-on resistors required for drive configuration - 9-position dipswitch set-up
- Dipswitch used for built-in self-test, step angle selection, current level selection, and optional idle current reduction.
- Standard power supply available to operate at least two stepping systems of any size with an auxiliary +5 VDC supply to facilitate DirectLOGIC PLCs and stepping motor drive interfaces.

## Four standard motors with connectorized pigtails

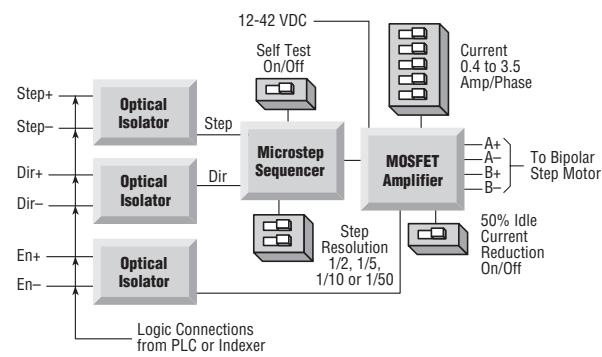
The SureStep™ stepping family has four standard motors to handle a wide range of automation applications such as woodworking, assembly, and test machines. Our square frame or "high torque" style stepping motors are the latest technology, resulting in the best torque to volume. We have NEMA 17, 23, and 34 mounting flanges and holding torque ranges from 83 oz-in to 434 oz-in. A 20 foot extension cable with locking connector is a standard option to interface any of the four stepping motors to the microstepping drive. The extension cable can be easily cut to length if desired.

### Drive



STD-DRV-4035

### Drive Block Diagram

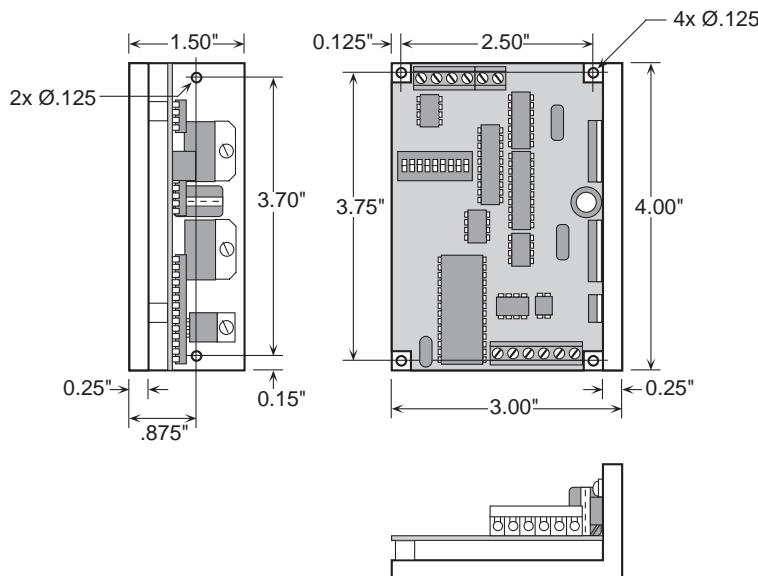


# Surestep™ STEPPING SYSTEMS

## SureStep™ Series Specifications – Microstepping Drive

Microstepping Drive		STP-DRV-4035
<b>Input Power (with power on red LED)</b>	12-42 VDC (including ripple voltage)	
<b>Output Power</b>	Output current selectable from 0.4 to 3.5 Amps/phase motor current (maximum output power is 140 W)	
<b>Current Controller</b>	Dual H-bridge Bipolar Chopper (3-state 20 kHz PWM with MOSFET switches)	
<b>Input Signals</b>	<b>Input Signal Circuit</b>	Opto-coupler input with 440 Ohm resistance (5 to 15 mA input current), Logic Low is input pulled to 0.8 VDC or less, Logic High is input 4 VDC or higher
	<b>Pulse Signal</b>	Motor steps on falling edge of pulse and minimum pulse width is 0.5 microseconds
	<b>Direction Signal</b>	Needs to change at least 2 microseconds before a step pulse is sent
	<b>Enable Signal</b>	Logic 0 will disable current to the motor (current is enabled with no hook-up or logic 1)
<b>DIP Switch Selectable Functions</b>	<b>Self Test</b>	Off or On (uses half-step to rotate 1/2 revolution in each direction at 100 steps/second)
	<b>Microstepping</b>	400 (200x2), 1,000 (200x5), 2,000 (200x10), or 10,000 (200x50) steps/rev
	<b>Idle Current Reduction</b>	0% or 50% reduction (idle current setting is active if motor is at rest for 1 second or more)
	<b>Phase Current Setting</b>	0.4 to 3.5 Amps/phase with 32 selectable levels
<b>Drive Cooling Method</b>	Natural convection (mount drive to metal surface if possible)	
<b>Dimensions</b>	3 x 4 x 1.5 inches	
<b>Mounting</b>	Use #4 screws to mount on wide side (4 screws) or narrow side (2 screws)	
<b>Connectors</b>	Screw terminal blocks with AWG 18 maximum wire size	
<b>Weight</b>	9.3 oz. (264 g)	
<b>Chassis Operating Temperature</b>	0 °C to 55 °C recommended, 70 °C maximum (use fan cooling if necessary)	
<b>Agency Approvals</b>	CE (complies with EN55011A and EN50082-1 (1992))	

## Dimensions

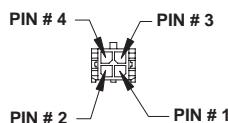


# SureStep™ STEPPING SYSTEMS

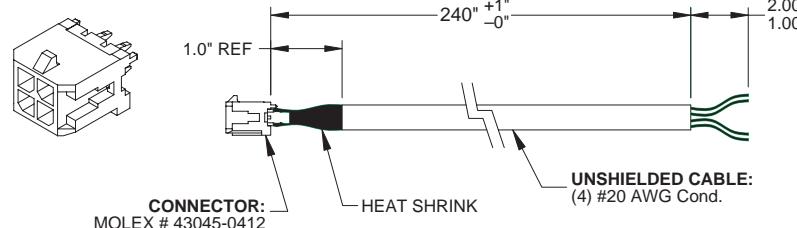
## SureStep™ Series Specifications – High Torque Bipolar Stepping Motors

Bipolar Stepping Motors				
<b>Stepping Motor Face Plate</b>	NEMA 17	NEMA 23	NEMA 23	NEMA 34
<b>Maximum Holding Torque</b>	5.2 lb-in 83 oz-in 0.59 Nm	11.4 lb-in 166 oz-in 1.29 Nm	18.4 lb-in 276 oz-in 2.08 Nm	27.1 lb-in 434 oz-in 3.06 Nm
<b>Rotor Inertia</b>	0.00006 lb-in-s <sup>2</sup> 0.45 oz-in <sup>2</sup> 0.0000068 kg-m <sup>2</sup>	0.00024 lb-in-s <sup>2</sup> 1.483 oz-in <sup>2</sup> 0.000027 kg-m <sup>2</sup>	0.00042 lb-in-s <sup>2</sup> 2.596 oz-in <sup>2</sup> 0.000047 kg-m <sup>2</sup>	0.0012 lb-in-s <sup>2</sup> 7.66 oz-in <sup>2</sup> 0.00014 kg-m <sup>2</sup>
<b>Rated Current</b>	2.0 A/phase	2.8 A/phase	2.8 A/phase	2.8 A/phase
<b>Basic Step Angle</b>	1.8° (2-phase motors with connectorized pigtail)			
<b>Weight</b>	0.7 lbs	1.50 lbs	2.2 lbs	3.85 lbs
<b>Shaft Runout</b>	0.002 in			
<b>Shaft Radial Play @ 1 lb load</b>	0.001 in max			
<b>Perpendicularity</b>	0.003 in			
<b>Concentricity</b>	0.002 in			
<b>Operating Temperature Range</b>	-20 °C to 50 °C (motor case temperature should be kept below 100 °C (212 °F))			
<b>Maximum Radial Load</b>	6.0 in/lb	15.0 in/lb	15.0 in/lb	39.0 in/lb
<b>Maximum Thrust Load</b>	6.0 in/lb	13.0 in/lb	13.0 in/lb	25.0 in/lb
<b>Agency Approvals</b>	130 °C Class B			
<b>Agency Approvals</b>	CE (complies with EN55014-1 (1993) and EN60034-1.5.11)			
<b>Design Tips</b>	Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. DO NOT connect or disconnect the step motor during operation. Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent thrust loading on bearings from minor mis-alignment.			
<b>Extension Cable - 20 Foot (motor to drive)</b>	<p style="text-align: center;"><b>Part Number STP-EXT-020</b></p> 			

## Extension Cable Wiring Diagram



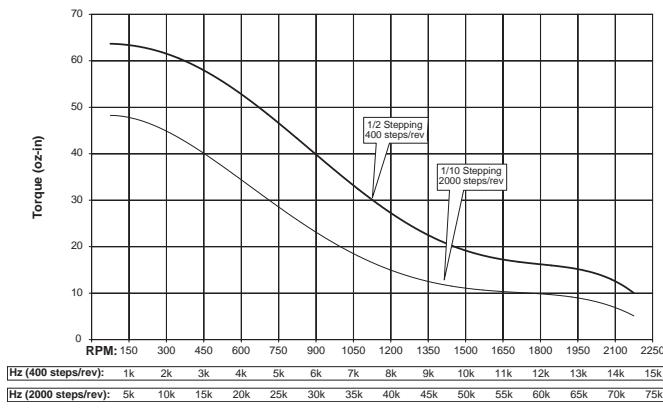
PIN #	COLOR
1	RED
2	WHITE
3	GREEN
4	BLACK



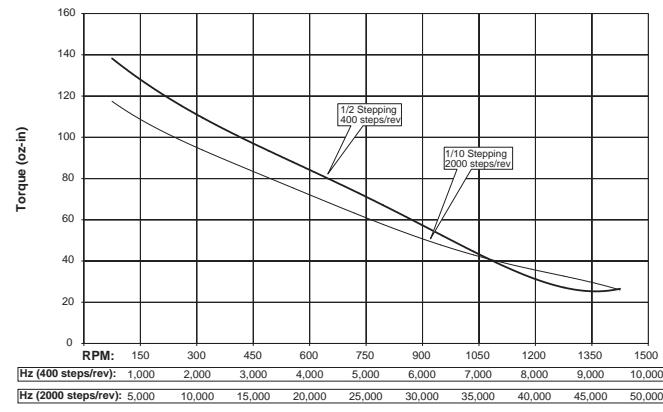
# Surestep™ STEPPING SYSTEMS

## Torque vs. Speed Chart

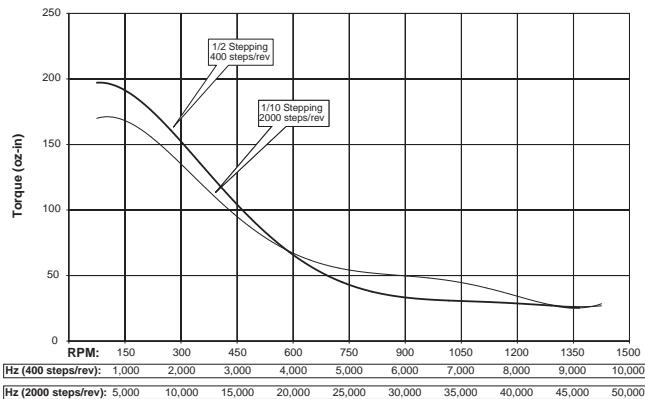
STP-MTR-17048



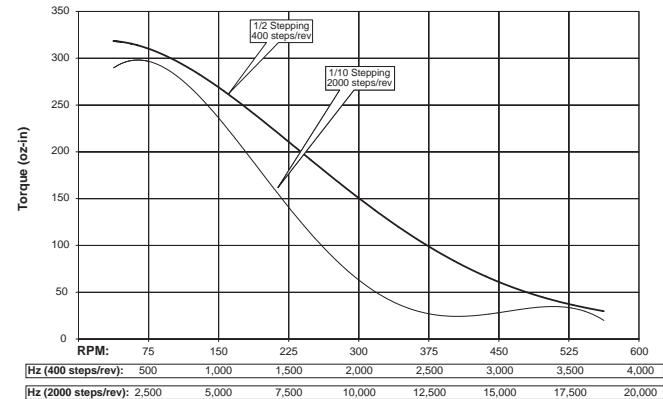
STP-MTR-23055



STP-MTR-23079



STP-MTR-34066

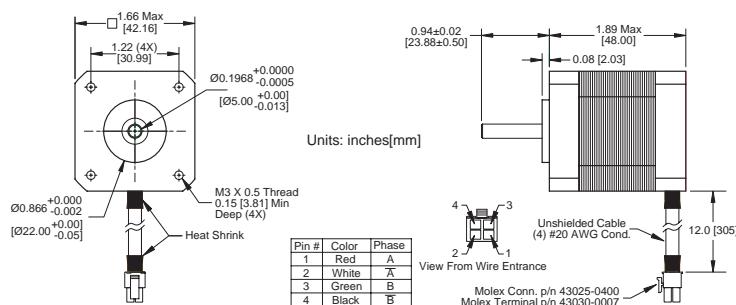


 **NOTE:** THE TORQUE VS. SPEED CURVE VALUES SHOWN ABOVE WERE OBTAINED AT NOMINAL AC INPUT VOLTAGE USING SURESTEP™ STEP MOTORS DESCRIBED IN THIS DATA SHEET, THE STP-PWR-3204 STEP MOTOR POWER SUPPLY AND FULL LENGTH STP-EXT-020 EXTENSION CABLE.

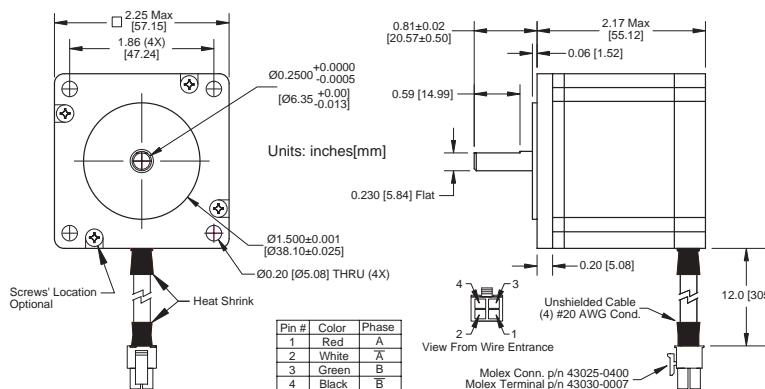
# SureStep™ STEPPING SYSTEMS

## Dimensions

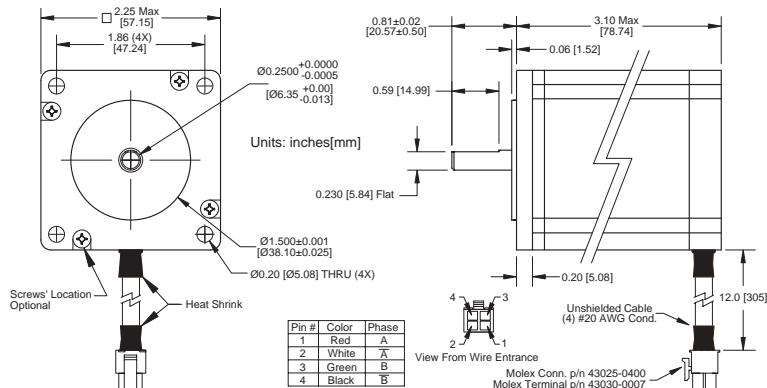
**STP-MTR-17048**



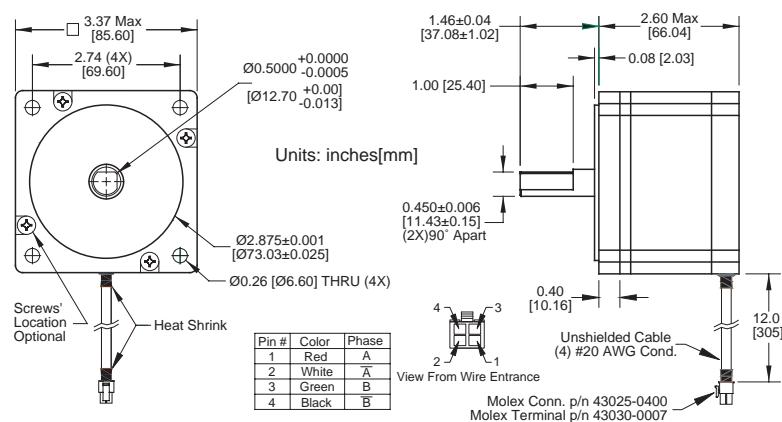
**STP-MTR-23055**



**STP-MTR-23079**



**STP-MTR-34066**

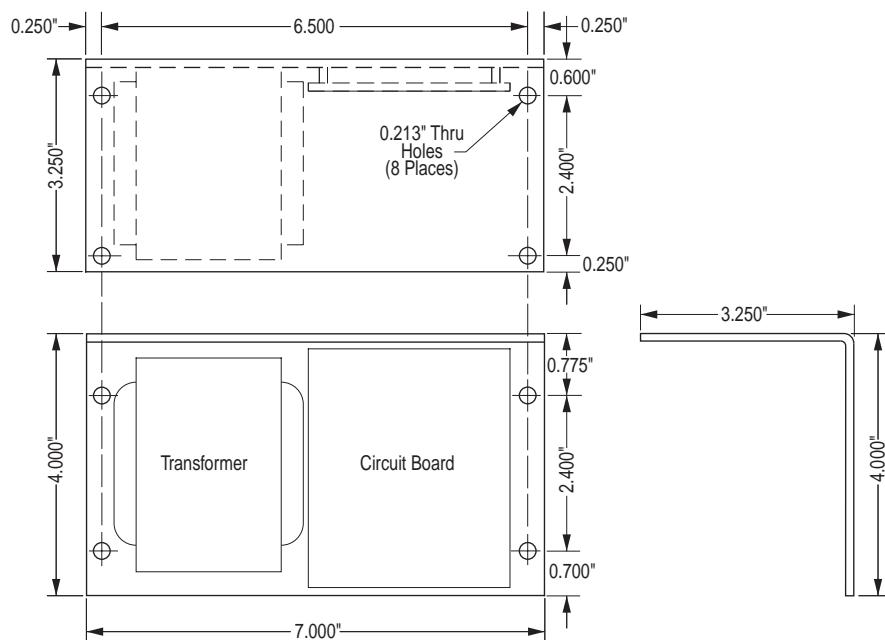


# Surestep™ STEPPING SYSTEMS

## SureStep™ Series Specifications – Stepping System Power Supply

Power Supply for Stepping System	STP-PWR-3204
<b>Input Power (fuse protected)</b>	1-phase, 120/240 VAC, 50/60 Hz, 150 va (Fuse: 3 A, form factor 3AG, fast acting)
<b>Input Voltage Range (switch selectable)</b>	120/240 VAC ±10%
<b>Inrush Current</b>	120 VAC < 12 A / 240 VAC < 14 A
<b>Motor Supply Output (linear unregulated, fuse protected and power on LED indicator)</b>	32 VDC @ 4 Amp (fully loaded) 35 VDC @ 1 Amp load 41 VDC @ no load (Fuse: 6 A, form factor 3AG, fast acting)
<b>Logic Supply Output (± 5% regulated, electronically overload protected and power on LED indicator)</b>	5 VDC @ 500 mA (Electronically Overload Protected)
<b>Operating Temperature Range</b>	0 °C to 50 °C full rated; derate current 1.1% per degree above 50 °C; 70 °C maximum
<b>Storage Temperature Range</b>	-55 °C to 85 °C
<b>Humidity</b>	95% (non-condensing) relative humidity maximum
<b>Cooling Method</b>	Natural convection (mount power supply to metal surface if possible)
<b>Dimensions</b>	4 x 7 x 3½ inches
<b>Mounting</b>	Use four (4) #8 or #10 screws to mount on either wide or narrow side.
<b>Weight</b>	6.5 lbs
<b>Connections</b>	Screw Terminal
<b>Agency Approvals</b>	UL, CSA and CE

## Dimensions

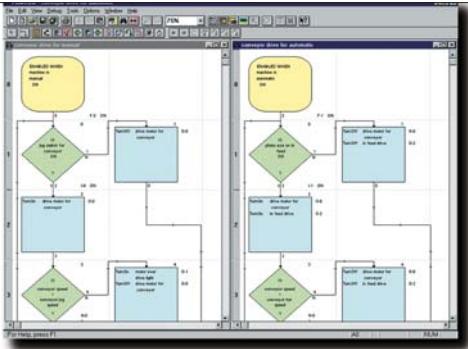


# SureStep™ STEPPING SYSTEMS

Motion Control with DirectLOGIC PLCs and SureStep™ Stepping Systems			
PLC Series	1 axis control	1-2 axis control	1-5 axis control
	<b>DL105</b> 	<b>DL05</b> 	<b>DL06</b>  
<b>Local I/O</b>	18	14	36
<b>Maximum Possible I/O</b>	18	30	100
<b>Built-In Pulse Outputs</b>	1 axis pulse output included with the PLC base unit. (DC output models only)		
<b>Maximum Velocity</b>	7,000 pulses/sec		10,000 pulses/sec
<b>Target Pulse Range</b>	-8,388,608 to +8,388,607 pulses		
<b>Minimum Velocity</b>	40 pulses/sec		
<b>Velocity Resolution</b>	10 pulses/sec		
<b>Accel/Decel Range</b>	0.1 to 10 sec		
<b>Position Control</b>	Trapezoidal Profiles		
<b>Velocity Control</b>	Velocity Levels		
<b>I/O Modules Pulse Outputs</b>	Not Applicable	<b>HO-CTRIO (1 axis per module)</b>  	
<b>Maximum Velocity</b>		25,000 pulses/sec	
<b>Target Pulse Range</b>		+ / - 2.1 billion pulses (31 bits plus sign)	
<b>Minimum Velocity</b>		40 pulses/sec	
<b>Velocity Resolution</b>		10 pulses/sec	
<b>Accel/Decel Range</b>		0.1 to 10 sec	
<b>Position Control</b>		Trapezoidal Profiles (linear & S-curve ramps)	
<b>Velocity Control</b>		Dynamic Velocity (controlled accel/decel)	
<b>Maximum Number of Modules</b>		1	4

# Surestep™ STEPPING SYSTEMS

## Motion Control with *DirectLOGIC* PLCs and SureStep™ Stepping Systems

PLC Series	1-16 axis control depending on base size and power supply budget	
	DL205	DL405
= popular choices		
<b>Local I/O</b>	256	640
<b>Maximum Possible I/O</b>	16,384	16,384
 <span style="margin-left: 100px;">PC-Based Control with Think &amp; Do: On your PC with Windows, or our embedded WinPLC</span>		
 <span style="margin-left: 100px;"><i>Integrate the motion control using the H2-CTRIO or T1H-CTRIO</i></span>		
I/O Modules Pulse Outputs	D2-CTRINT (1 axis per module)	H2-CTRIO T1H-CTRIO (2 axis per module) H4-CTRIO
<b>Maximum Velocity</b>	5,000 pulses/sec	25,000 pulses/sec
<b>Target Pulse Range</b>	-8,388,608 to +8388,607 pulses	+/- 2.1 billion pulses
<b>Minimum Velocity</b>		40 pulses/sec
<b>Velocity Resolution</b>		10 pulses/sec
<b>Accel/Decel Range</b>		0.1 to 10 sec
<b>Position Control</b>	Trapezoidal Profiles (linear and S-curve ramps)	
<b>Velocity Control</b>	Dynamic Velocity (controlled accel/decel)	
<b>Maximum Number of Modules</b>	1	1-8